

Dynamic Programming

ECON 34430: Topics in Labor Markets

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Agenda

① Introduction

- Cake eating, direct approach and Bellman
- Stochastic Dynamic programming

② Numerical methods

- Value function iteration
- Policy function iteration
- Continuous space and collocation

③ General formulation and properties

④ Estimation

- Rust assumptions
- CCP methods
- General estimation



Introduction



Cake eating problem

- $t = 0$, have a cake of size W_0
- preferences are

$$\sum_{t=0}^T \beta^t u(c_t)$$

- choose $(c_0 \dots c_T)$ to maximize present value

$$\begin{aligned} \max_{c_0 \dots c_T} & \sum_{t=0}^T \beta^t u(c_t) \\ \text{s.t.} & \sum_{t=0}^T c_t \leq W_0 \end{aligned}$$



Finite horizon - Direct approach

- write the Lagrangian

$$\sum_{t=0}^T \beta^t u(c_t) - \lambda \left(\sum_{t=0}^T c_t - W_0 \right)$$

- take FOCs:

$$\forall t, \quad \beta^t u'(c_t) = \lambda \quad \text{and} \quad \sum_{t=0}^T c_t = W_0$$

- which implies the common Euler equation:

$$u'(c_t) = \beta u'(c_{t+1})$$

- from which we get with log utility

$$c_t = \frac{\beta^t}{\lambda} = \beta^t W_0 \frac{1 - \beta^{T+1}}{1 - \beta}$$

- note that FOC is only necessary, need to impose to achieve optimality



Infinite horizon - Direct approach

- write the Lagrangian

$$\sum_{t=0}^{\infty} \beta^t u(c_t) - \lambda \left(\sum_{t=0}^{\infty} c_t - W_0 \right)$$

- take FOCs:

$$\forall t, \quad \beta^t u'(c_t) = \lambda \quad \text{and} \quad \sum_{t=0}^{\infty} c_t = W_0$$

- which still implies the common Euler equation:

$$u'(c_t) = \beta u'(c_{t+1})$$

- from which we get with log utility

$$c_t = \frac{\beta^t}{\lambda} = \beta^t \frac{W_0}{1 - \beta}$$

- note that FOC is only necessary, need to impose $\sum_{t=0}^{\infty} c_t = W_0$ to achieve optimality



Infinite horizon - Recursive formulation

- Define:

$$V(W_0) = \max_{c_0 \dots c_\infty} \sum_{t=0}^{\infty} \beta^t u(c_t) \text{ s.t. } \sum_{t=0}^{\infty} c_t \leq W_0$$

- next, we split the max into today and all of the future

$$V(W_0) = \max_{c_0} \left[u(c_0) + \beta \max_{c_1 \dots c_\infty} \sum_{t=0}^{\infty} \beta^t u(c_{t+1}) \right]$$
$$\text{s.t. } \sum_{t=1}^{\infty} c_t \leq W_0 - c_0$$

- and so

$$V(W_0) = \max_c u(c) + \beta V(W_0 - c)$$



Infinite horizon - Recursive formulation 2

- We have:

$$V(W_0) = \max_c u(c) + \beta V(W_0 - c)$$

- where $V(\cdot)$ is not known, but defined implicitly.
- We need to solve for $c(W_0)$ and $V(W_0)$ for all W_0
- if W we can take FOC to get

$$\begin{aligned}u'(c) &= \beta V'(W_0 - c) \\V'(W_0) &= \beta V'(W_0 - c)\end{aligned}$$

- which gives us back our Euler equation $u'(c_t) = \beta u'(c_{t+1})$



Infinite horizon - Recursive formulation 3

- Is this sufficient for optimality of the original problem?
- Remember that the Euler equation alone was not sufficient in the direct attack
- We can replace the consumption rule in to get

$$c_t = \beta^t c_0 = (1 - \beta)\beta^t W_0$$

- In some cases, it would also require a **transversality condition**



Stochastic Dynamic programming

- We now want to consider the stochastic case
- The agents will face a series of ϵ_t taste shocks, which follow a Markov Process $\pi_{ij} = Pr[\epsilon_t = j | \epsilon_{t-1} = i]$
- We denote a history of shocks as $h^t = (\epsilon_0 \dots \epsilon_t)$ with $\epsilon_t(h^t) = \epsilon_t$ and we write $\pi(h^t)$ its overall probability
- Now for every history $\epsilon^t = (\epsilon_0 \dots \epsilon_t)$ the agent can choose a consumption $c_t(\epsilon^t)$.
- We write the general problem as:

$$\begin{aligned} & \max_{c_0 \dots c_\infty} \sum_{t=0}^{\infty} \beta^t \sum_{h^t} \epsilon_t(h^t) u(c_t(h^t)) \pi_t(h^t) \\ & \text{s.t. } \forall t, h^t \quad \sum_{\tau} c_\tau(h^t(0, \tau)) \leq W_0 \end{aligned}$$

Stochastic Dynamic programming

- We can write the Lagrangian

$$\sum_{t=0}^{\infty} \beta^t \sum_{h^t} \epsilon_t(h^t) u(c_t(h^t)) \pi_t(h^t) - \sum_t \sum_{h^t} \lambda_{h^t} \left[\sum_{\tau} c_{\tau}(h^t(0, \tau)) - W_0 \right]$$

- and we can take FOC conditions for each $c_t(h^t)$

$$\beta^t \epsilon_t(h^t) u'(c_t(h^t)) \pi_t(h^t) - \sum_{\tau \geq t} \sum_{h^{\tau} \in \Gamma_{\tau}(h^t)} \lambda_{h^{\tau}}$$

where $\Gamma_{\tau}(h^t) = \{h^{\tau} \text{ s.t. } h^{\tau}(0, \tau) = h^t\}$

Stochastic Dynamic programming

- We can combine FOC of $c_t(h^t)$ and $c_{t+1}(h^{t+1})$

$$\begin{aligned} & \beta^t \epsilon_t(h^t) u'(c_t(h^t)) \pi_t(h^t) \\ &= \sum_{\tau \geq t} \sum_{h^\tau \in \Gamma_\tau(h^t)} \lambda_{h^\tau} \\ &= \sum_{\tau \geq t} \left[\sum_j \lambda_{[h^t: \epsilon_j]} + \sum_{h^\tau \in \Gamma_\tau(h^t: \epsilon_j)} \lambda_{h^\tau} \right] \\ &= \sum_j \sum_{\tau \geq t+1} \sum_{h^\tau \in \Gamma_\tau(h^t: \epsilon_j)} \lambda_{h^\tau} \\ &= \sum_j \beta^{t+1} \epsilon_{t+1}(h^t: \epsilon_j) u'(c_{t+1}(h^t: \epsilon_j)) \pi_t(h^t: \epsilon_j) \end{aligned}$$

Stochastic Dynamic programming

- we can rewrite

$$\epsilon_t u'(c_t(h^t)) = \beta \sum_j \epsilon_j u'(c_{t+1}(h^t:\epsilon_j)) \frac{\pi_t(h^t:\epsilon_j)}{\epsilon_t(h^t)\pi_t(h^t)}$$

$$\epsilon_t u'(c_t(h^t)) = \beta \sum_j \epsilon_j u'(c_{t+1}(h^t:\epsilon_j)) \pi_{ij}$$

$$\epsilon_t u'(c_t) = \beta \mathbb{E}[\epsilon_j u'(c_{t+1}) | \epsilon_t]$$

- where we recovered the Euler equation !

Stochastic Dynamic programming

- we go back to the original formulation

$$V(W_0, \epsilon_0) = \max_{c_0 \dots c_\infty} \sum_{t=0}^{\infty} \beta^t \sum_{h^t} \epsilon_t(h^t) u(c_t(h^t)) \pi_t(h^t)$$
$$\text{s.t. } \forall t, h^t \quad \sum_{\tau} c_\tau(h^t(0, \tau)) \leq W_0$$

- we apply the same trick as before, we split the max into today and the future

$$\max_{c_0 \dots c_\infty} \sum_{t=0}^{\infty} \beta^t \sum_{h^t} \epsilon_t(h^t) u(c_t(h^t)) \pi_t(h^t) =$$
$$\max_{c_0} \epsilon_0 u(c_0) +$$
$$+ \beta \max_{c_1 \dots c_\infty} \sum_{t=0}^{\infty} \beta^t \sum_{h^{t+1} \in \Gamma_{t+1}(\epsilon_0)} \epsilon_{t+1}(h^{t+1}) u(c_{t+1}(h^{t+1})) \pi_{t+1}(h^{t+1})$$

Stochastic Dynamic programming

- and we split the second part as before according the first realization in the path

$$\begin{aligned} & \sum_{t=0}^{\infty} \beta^t \sum_{h^{t+1} \in \Gamma_{t+1}(\epsilon_0)} \epsilon_t(h^{t+1}) u(c_{t+1}(h^{t+1})) \pi_{t+1}(h^{t+1}) \\ &= \sum_{t=0}^{\infty} \beta^t \sum_j \sum_{h^{t+1} \in \Gamma_{t+1}(\epsilon_0: \epsilon_j)} \epsilon_{t+1}(h^{t+1}) u(c_{t+1}(h^{t+1})) \pi_t(h^{t+1}) \\ &= \sum_j \pi_{ij} \sum_{t=0}^{\infty} \beta^t \sum_{h^{t+1} \in \Gamma_{t+1}(\epsilon_0: \epsilon_j)} \epsilon_{t+1}(h^{t+1}) u(c_{t+1}(h^{t+1})) \pi_{t+1}(h^{t+1}) \\ &= \sum_j \pi_{ij} V(W_0 - c_0, \epsilon_j) \end{aligned}$$

Stochastic Dynamic programming

- We end up with the following Bellman equation:

$$V(W_0, \epsilon_0) = \max_c \epsilon_0 u(c) + \beta \sum_j V(W_0 - c_0, \epsilon_j)$$

- where we can also take FOC to get

$$\epsilon_0 u'(c) = \beta \sum_j V_1(W_0 - c_0, \epsilon_j)$$

$$V_1(W_0, \epsilon_0) = \beta \sum_j V_1(W_0 - c_0, \epsilon_j)$$

References

